

## SCENARIOS





Diablo Robotics is capable of operating in various scenarios such as delivering parcels and meals. After secondary development, it can be adapted for applications like VR usage, gas detection and security patroling.

Diablo Robotics is also a standout presence at international conferences such as the International Conference on Robotics and Automation (ICRA), the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), GITEX, and more.

## PARAMETERS

| Net weight               | 22.9KG        | Battery life in standing mode               | ≈ 3 hours in 25°C       |
|--------------------------|---------------|---|-------------------------|
| Dimensions (Standing)    | 540×371×491mm | Battery life in squatting mode              | ≈ 15min in 25°C         |
| Dimensions (Creeping)    | 540×371×270mm | Creeping mode Maximum continuous travel     | ≈ 3 hours in 34°C       |
| Maximum load in standing | 4kg           | Squattinging mode Maximum continuous travel | ≈ 3 hours in 34°C       |
| Maximum load in creeping | 80kg          | Standing mode jumping height                | ≈ 8 cm(Without loading) |
| Noise during operating   | <49dB         | Maximum travel speed                        | 2m/s                    |

# DIABLO

World's First Direct-Drive Self-Balancing Wheeled-Leg Robot



#### DIRECT DRIVE TECHNOLOGY

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## PRODUCT INTRODUCTION

Diablo Robotics is a direct-drive agile bipedal robot — a balancing mobile platform equipped with powered wheels on its feet. It features 6 degrees of freedom (DoF), enabled by six M1502D direct-drive joint motors, allowing movement in six directions. Diablo perfectly combines the speed advantages of wheeled AGVs with the mobility and obstacle-crossing capabilities of legged robots, enabling efficient and flexible movement across various terrains. It can quietly accompany you like a reliable companion.



## FEATURES

Easy

Friendly Development

Maintenance Reliable

Really

Drive

Efficient

Solution

#### Diablo provides an open SDK

Diablo can also be installed with other hardware modules by users, including installing Lidar, Anti-collision module, GPS, etc.



## PERFORMANCE

#### Aerial Descent

Automatically balances itself upon landing.

### The Head of Diablo Remains Stable and Balanced

Maintaining its flat across various terrains.

#### Obstacle-Climbing Height

8cm.

## Ability to maintain balance stably

When the Diablo is running, even if its feet are standing on different terrains, it can keep the body moving stably through it.

#### Standing&Creeping Models

The head height can be adjusted by 10 cm to assist in crossing obstacles.







Since there is no loss in the gear box, the direct drive solution has a longer service life and the system is more stable. The flange connection design also makes the maintenance and repair of the equipment simple and easy.

Long lasting battery life

3 hours high-speed running in creeping mode.

3 hours low-speed running in standing mode.

Since there is no friction in the transmission mechanism, the direct has a higher energy utilization efficiency and can provide a 30% increase battery life. Equipment can spend moretime working and less time returning to recharge, greatly increasing.

The modular design makes product solution design more efficient, shortening the design cycle of the wheeled robot chassis by at least 20%, making it easier to develop, install and debug.